

Formula Sheet**1. Kinematics & Dynamics**

A vector equation in 2D is actually two separate equations – one for each perpendicular axis. You get to choose (or may be told) which axes to use, and which direction is positive for each axis 😊.

$$\vec{v} = \frac{\Delta \vec{x}}{\Delta t} \quad (2.1)$$

$$\vec{a} = \frac{\Delta \vec{v}}{\Delta t} \quad (2.2)$$

$$\left. \begin{aligned} x &= x_0 + v_{av,x}t \\ \text{where } v_{av,x} &= \frac{v_{0x} + v_x}{2} \\ v_x &= v_{0x} + a_x t \\ x &= x_0 + v_{0x}t + \frac{1}{2}a_x t^2 \\ v_x^2 &= v_{0x}^2 + 2a_x(x - x_0) \end{aligned} \right\} \dots \text{and sim. for y cmpts} \quad (2.3)$$

$$\begin{aligned} \vec{R} &= \vec{A} + \vec{B} \\ \Rightarrow R_x &= A_x + B_x ; R_y = A_y + B_y \end{aligned} \quad (3.1)$$

$$h = \frac{v_{0y}^2}{2g} ; R = \frac{v_0^2 \sin 2\theta_0}{g} \quad (3.2)$$

$$\vec{v}_{\text{plane rel to gnd}} = \vec{v}_{\text{plane rel to air}} + \vec{v}_{\text{air rel to gnd}} \quad (3.3)$$

$$\vec{F}_{\text{net}} = m\vec{a} \quad (4.1)$$

$$f_s \leq \mu_s N ; f_k = \mu_k N \quad (5.1)$$

$$F_D = \frac{1}{2} C \rho A v^2 \quad (5.2)$$

$$F_S = 6\pi r \eta v \quad \text{if motion is slow or medium is dense} \quad (5.3)$$

$$F = k\Delta L \quad (5.4)$$

$$Y = \frac{F/A}{\Delta L/L_0} \quad (5.5)$$

$$S = \frac{F/A}{\Delta x/L_0} \quad (5.6)$$

$$B = \frac{F/A}{\Delta V/V_0} \quad (5.7)$$

$$\Delta\theta = \frac{\Delta s}{r} \quad (6.1)$$

$$\omega = \frac{\Delta\theta}{\Delta t} \quad \text{so} \quad \omega = \frac{2\pi}{T} ; v = r\omega \quad (6.2)$$

$$a_c = \frac{v^2}{r} = r\omega^2 \quad (6.3)$$

$$F_c = \frac{mv^2}{r} = mr\omega^2 \quad (6.4)$$

$$F_g = \frac{GMm}{r^2} ; g = \frac{GM}{r^2} \quad (6.5)$$

$$\frac{T_1^2}{T_2^2} = \frac{r_1^3}{r_2^3} \quad (6.6)$$

$$W = Fd \cos \theta \quad (7.1)$$

$$KE = \frac{1}{2}mv^2 ; PE_g = mgh ; PE_s = \frac{1}{2}kx^2 \quad (7.2)$$

$$W_{\text{net}} = \Delta KE_{\text{bulk objects}} + \Delta PE_{\text{bulk objects}} + \Delta E_{\text{thermal, from friction between bulk objects}} + \Delta E_{\text{microscopic, from chemical, food, nuclear, etc.}} \quad (7.3)$$

$$\text{where } \Delta E_{\text{thermal, from friction between bulk objects}} = f_k d \quad (7.4)$$

$$P = \frac{\text{Energy transferred or converted}}{\text{time taken}} \quad (7.5)$$

$$\vec{p} = m\vec{v} \quad (8.1)$$

$$\vec{F}_{\text{net}} = \frac{\Delta \vec{p}}{\Delta t} \quad (8.2)$$

$$\text{Impulse} = \vec{F}_{\text{net}} \Delta t = \Delta \vec{p} \quad (8.3)$$

$$a = \frac{v_e \Delta m}{m \Delta t} - g \quad (8.4)$$

2. Mathematical Formulae

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \quad (M.1)$$

$$\sin \theta = \frac{\text{opp}}{\text{hyp}} ; \cos \theta = \frac{\text{adj}}{\text{hyp}} ; \tan \theta = \frac{\text{opp}}{\text{adj}} \quad (M.2)$$

$$a^2 = b^2 + c^2 - 2bc \cos \theta \quad (M.3)$$

3. Fundamental constants and physical properties: usually given in the question, or in Urone, or ask invigilator

...and also: $g = 9.80 \text{ ms}^{-2} ; \rho_{\text{water}} = 997 \text{ kg/m}^3$